GENERAL

# quick reference for the mechanical engineering pe exam

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## Quick Reference for the Mechanical Engineering PE Exam: Your Ultimate Study Companion

The Professional Engineer (PE) exam is the gateway to a career of professional credibility, higher earnings, and the opportunity to sign off on critical projects. For mechanical engineers, the exam is a comprehensive test of knowledge across mechanics, thermodynamics, materials science, fluid dynamics, and more. Preparing for the exam can feel overwhelming, especially when you're juggling coursework, a job, and a personal life. That's why a **quick reference for the mechanical engineering PE exam** can be a game changer. This article offers a meticulously curated, easy to scan reference guide that condenses the most essential formulas, constants, unit conversions, and conceptual insights you'll need to ace the test.

## Why a Quick Reference Matters

Exam day is a marathon, not a sprint. Even if you've spent months studying, you'll still need to locate formulas quickly. A well organized quick reference eliminates the mental gymnastics of searching through notes, textbooks, or the exam handbook. It keeps you focused on solving problems rather than hunting for equations. Moreover, the exam allows you to bring a reference book, and many candidates choose a compact, well structured guide that they can flip through in seconds.

Below, we'll walk through the key sections that every mechanical engineering PE candidate should master. Each section is broken into digestible sub headings, bullet points, and concise explanations. Feel free to print this out, bind it into a pocket size binder, or save it as a PDF for on the go review.

## 1. Fundamental Units & Conversion Factors

All mechanical engineering problems are expressed in SI units, but the exam may occasionally present values in imperial units. A solid grasp of unit conversions is essential.

- Length: 1 /inch = 2.54 /cm, 1 /foot = 0.3048 /m, 1 /mile = 1609.34 /m
- Mass: 1 /pound = 0.453592 /kg, 1 /ounce = 28.3495 /g
- Force: 1 /lbf = 4.44822 /N
- Pressure: 1 /psi = 6894.76 /Pa, 1 /bar = 100 /kPa, 1 /atm = 101.325 /kPa
- Energy: 1 /BTU = 1055.06 /J, 1 /kWh = 3.6 /MJ
- Temperature: °F to °C: (°F /– /32) /× /5/9; °C to K: °C /+ /273.15

Remember that the exam allows you to use a reference book, but you must still know the base equations. Keep these conversion factors at the top of your quick reference for instant recall.

## 2. Material Properties & Mechanics

### 2.1 Stress & Strain Relationships

Understanding the stress–strain curve is the cornerstone of mechanical design. Below are the key equations and definitions.

- Young’s Modulus (E): \\(E = \\frac{\\sigma}{\\varepsilon}\\) (<2 Ò 7G&W70, ;R Ò 7G ain)
- Poisson’s Ratio (;Ò“ \\(;Ò Ò ÕÅÆg ac{\\varepsilon_{\\text{transverse}}}{\\varepsilon_{\\text{axial}}}\\)
- Shear Modulus (G): \\(G = \\frac{E}{2(1+;Ò—ÕÅÂ•
- Bulk Modulus (K): \\(K = \\frac{E}{3(1-2;Ò—ÕÅÂ•
- Yield Strength (<7’“ Stress at which material begins to deform plastically.
- Ultimate Tensile Strength (<7R“ Maximum stress material can withstand.

### 2.2 Beam Theory

Beam deflection, bending stress, and shear stress formulas are essential for structural calculations.

- Bending Stress: \\(\\sigma = \\frac{M\\,c}{I}\\)
- Bending Moment for a Simply Supported Beam: \\(M_{\\text{max}} = \\frac{wL^2}{8}\\) (uniform load w)
- Deflection for a Uniform Load: \\(\\delta_{\\text{max}} = \\frac{5wL^4}{384EI}\\)
- Shear Stress: \\(\\tau = \\frac{VQ}{Ib}\\)

### 2.3 Fatigue & Failure Criteria

When designing for cyclic loading, you’ll encounter S–N curves and fatigue life predictions.

- Endurance Limit (<6R“ Stress amplitude below which a material can endure infinite cycles.
- Stress Concentration Factor (Kt): \\(K_t = \\frac{\\sigma_{\\text{max}}}{\\sigma_{\\text{nominal}}}\\)
- Failure Theories:

  Maximum Stress (Tresca)
- Maximum Strain (Rankine)
- Von Mises

## 3. Thermodynamics & Heat Transfer

### 3.1 State Properties & Ideal Gas Laws

Recall the ideal gas equations and specific heat relationships.

- Ideal Gas Law: \\(PV = nRT\\) or \\(pV = mRT\\) (m = mass)
- Specific Heats: \\(c_p\\) and \\(c_v\\); \\(c_p - c_v = R\\)
- Enthalpy Change: \\(\\Delta h = c_p \\Delta T\\)
- Entropy Change for Ideal Gas: \\(\\Delta s = c_p \\ln\\frac{T_2}{T_1} - R \\ln\\frac{p_2}{p_1}\\)

### 3.2 Energy Balance & Efficiency

Energy conservation and efficiency formulas are key for evaluating thermal machines.

- First Law for a Closed System: \\(9ER Ò Ò W\\)
- Efficiency of a Heat Engine: \\(\\eta = \\frac{W_{\\text{out}}}{Q_{\\text{in}}}\\)
- Coefficient of Performance (COP) for a Refrigerator: \\(COP = \\frac{Q_{\\text{cool}}}{W_{\\text{in}}}\\)
- Refrigeration Cycle (Carnot): \\(COP_{\\text{Carnot}} = \\frac{T_c}{T_h - T_c}\\)

### 3.3 Heat Transfer Coefficients

Use these correlations for conduction, convection, and radiation.

- Conduction: \\(q = \\frac{kA9EG×´ÇÕÅÂ•
- Convection (Newton’s Law): \\(q = hA(T_{\\text{fluid}} - T_{\\text{surface}})\\)
- Radiation: \\(q = ;SÃA(T_{\\text{surface}}^4 - T_{\\text{ambient}}^4)\\)
- Reynolds Number (Re): \\(Re = \\frac{< dG×³¼}\\)

- Nusselt Number (Nu): \\(Nu = \\frac{hD}{k}\\)

# 4. Fluid Mechanics & Dynamics

## 4.1 Continuity & Bernoulli

These equations are the backbone of most fluid problems.

- Continuity: \\(A_1v_1 = A_2v_2\\)
- Bernoulli (steady, incompressible): \\(p + ½< eã" ² Ágh = \\text{constant}\\)
- Pressure Drop in Pipes: \\(\\Delta p = f \\frac{L}{D} \\frac{< eã'×³'ÕÅÂ’ „F &7™epeisbach)

## 4.2 Dimensionless Numbers

These numbers help you assess flow regimes and scaling.

- Reynolds Number (Re): \\(Re = \\frac{< dG×³¼}\\)
- Mach Number (M): \\(M = \\frac{v}{c}\\) (c = speed of sound)
- Froude Number (Fr): \\(Fr = \\frac{v}{\\sqrt{gL}}\\)
- Weber Number (We): \\(We = \\frac{< eã$Ç×³Ã}\\)

## 4.3 Pump & Turbine Efficiency

Efficiency equations help evaluate performance.

- Pump Power: \\(P = \\frac{< u ‡×³·}\\)
- Turbine Power: \\(P = \\frac{< u ‡×³·}\\) (same form, but ;r —2 GW&&–æR Vff–6–Væ7’•
- Specific Speed (ns): \\(n_s = \\frac{n\\sqrt{Q}}{H^{3/4}}\\)

# 5. Dynamics & Vibrations

## 5.1 Kinematics & Equations of Motion

For single degree of freedom (SDOF) systems, these equations are fundamental.

- Equation of Motion: \\(m\\ddot{x} + c\\dot{x} + kx = F(t)\\)
- Natural Frequency (undamped): \\(\\omega_n = \\sqrt{\\frac{k}{m}}\\)
- Damping Ratio (;b“ \\(\\zeta = \\frac{c}{2\\sqrt{mk}}\\)
- Steady State Amplitude: \\(X = \\frac{F_0}{\\sqrt{(k-m\\omega^2)^2 + (c\\omega)^2}}\\)

## 5.2 Modal Analysis

Modal superposition is essential for complex systems.


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